Statistical methods – an introduction (SS 2022)

Problem set 8

1. In this problem set, the (measurement) error Δx of a quantity x is, as usual, an abbreviation for σ_x , i.e., if the actual measurement is $x = x_m + \delta x$, then $E(x) = x_m$, and $\Delta x = \sqrt{Var(x)} = \sqrt{E\{(\delta x)^2\}}$.

2. For calculating variances and covariances, use the calculation rules provided in Chap. 6 of the script, resulting from a linearization. In particular, remember the last equation on page 134.

Problem 1 [2 points] Error propagation

Suppose a function

$$f(x,y) = x + y,$$

where x and y are not independent. What is the corresponding squared error, $(\Delta f)^2$? Now, let y = g(x) and re-calculate $(\Delta f)^2$ as a function of $(\Delta x)^2$ by determining cov(x, g(x)).

Show that the result is identical with the squared error $(\Delta f)^2$ when *directly* calculating this quantity for the expression

$$f(x) = x + g(x).$$

Problem 2 [5 points] Wind-momentum and luminosity

[Note: In the following, 'logarithmic' refers to the logarithm with base 10.]

The theory of radiation driven winds predicts a linear relation between the logarithmic luminosity, $\log L'$, and the logarithmic 'modified' wind-momentum rate, $\log D'$, of a hot star ($T_{\rm eff} > 10,000$ K), where

$$L' = T_{\text{eff}}^{\prime 4} R_*^{\prime 2} D' = \dot{M}' v_{\infty}' R_*^{\prime 0.5}$$

and the primes indicate convenient normalizations (such that all quantities are dimensionless). T_{eff} and R_* are stellar effective temperature and radius, and \dot{M} and v_{∞} are the mass-loss rate and the terminal velocity of the corresponding wind, respectively.

Unfortunately, typical diagnostics does not directly yield the mass-loss rate, but a related quantity,

$$Q' = \frac{M'}{R_*'^{3/2}}.$$

Note: $Q', T'_{\text{eff}}, R'_{*}, v'_{\infty}$ are independent quantities!

a) Which normalization quantities would be useful for the first of the above equations $(L' = \ldots)$?

- b) In order to check the theoretical predictions or to use the observed relation, one has to plot $\log D'$ vs. $\log L'$, and to perform a linear regression. To obtain meaningful results and errors, the covariance between both quantities needs to be accounted for! Calculate the covariance matrix for $(\log L', \log D')$ in terms of $Var(\log T'_{\text{eff}})$, $Var(\log R'_{*}), Var(\log Q')$ and $Var(\log v'_{\infty})$.
- c) In the above considerations, $Var(\log x)$ corresponds to

$$Var(\log x) = \sigma^2(\log x) \approx \left(\Delta \log(x)\right)^2 = \left(\log(x + \Delta x) - \log(x)\right)^2.$$

Show that for $\Delta x/x \ll 1$, $Var(\log x)$ can be approximated in terms of $\frac{\Delta x}{x}$. Derive the corresponding relation, and convince yourself about the validity of this approximation, by using appropriate examples (numbers).

d) As outlined in b), a typical plot displays $\log D'$ vs. $\log L'$. From theory, this should result in a linear relation (at least for objects of not too different spectral type), and one of the interesting questions relates to the slope of this relation, m. To "measure" this slope, one performs a linear regression, i.e., minimizes the corresponding χ^2 from a series of measurements for different objects, i,

$$\chi^2 = \sum_{i}^{N} \left(\frac{y_i - (mx_i + b)}{\sigma_i} \right)^2.$$

 y_i corresponds to $\log D'_i$, x_i to $\log L'_i$, b is the other regression parameter, the intercept, and σ_i the error. Contrasted to the standard approach, however, in our case one has also to consider the errors on the x-axis, and the correlation between $\log D'$ and $\log L'$. This can be achieved by using the same algorithm, however interpreting now σ_i as the *total* error of the devation between y_i and the theoretically expected relation:

$$\sigma_{\text{tot},i} =: \Delta l_i, \text{ with } l_i = \log D'_i - (m \log L'_i + b).$$

Derive Δl_i using your results from problem b). Note that m and b have to be considered as constants. Both values can be derived by an iterative approach, but here we assume that they are already known.

When comparing with the "standard approach" ($\Delta x_i = 0$), there is an additional term in the expression for $\sigma_{\text{tot},i}$. When is this additional term larger than zero, i.e., under which conditions is the total error larger than the error for $\log D'_i$ alone? Quantify your result, by adopting ($\Delta T_{\text{eff}}/T_{\text{eff}}$) = 0.1, and ($\Delta R_*/R_*$) = 0.3. (If you would need other errors, you have done something wrong.)

Problem 3 [5 points] Transformed covariance matrix

Assume that you can independently measure the mass, m, and velocity, v, of a particle, and that there are no systematic errors. The relative measurement errors shall be known and constant, i.e., loosely speaking, $\Delta m/m = a$ and $\Delta v/v = b$. More precisely, we assume $\sigma_m/m_m = a$ and $\sigma_v/v_m = b$ (see top of this problem set).

a) Write down the covariance matrix for m and v.

- b) Calculate the corresponding (transformed) covariance matrix for the momentum p and kinetic energy E of the particle, and express the matrix elements in terms of p_m, E_m, a and b, where p_m and E_m are the 'true' values of p and E
- c) Determine the (linear) correlation coefficient, $\rho(p, E)$, in dependence of a, b, and derive its value for the three cases a = b, a = 0, and b = 0, respectively. What do you conclude, particularly from the results for a = 0 and b = 0, respectively?

Have fun, and much success!