

Numerical simulations of collisions between porous pre-planetesimals

Roland Speith

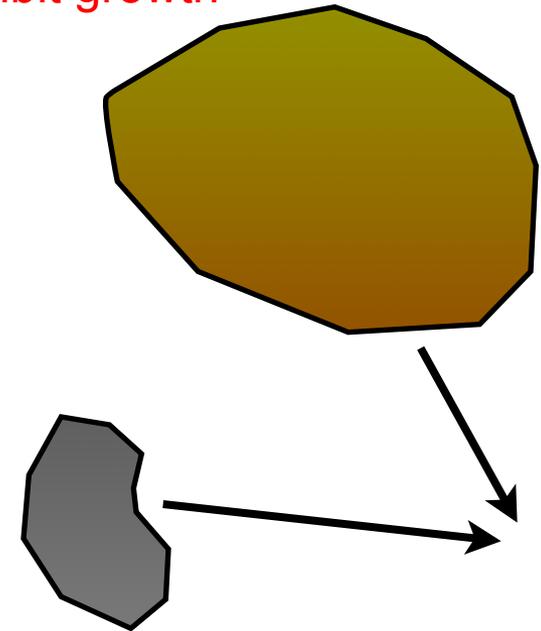
with R.J. Geretshauser, F. Meru, Ch. Schäfer

05/09/2012



Modelling Two-Body Collisions of Porous Objects

- Aim: **Parameterization** of **outcome** of 2-body collisions
 - In particular to get realistic **sticking** and **fragmentation conditions**, as **destructive collisions**, **fragmentation**, and **bouncing inhibit growth**
- The **collisional outcome** depends on:
 - **Size** and **shape** of target and projectile
 - **Impact velocities**
(relative velocities due to gas drag and collision history)
 - **Impact parameter** / impact angle
 - **Material composition** and **structure** of target and projectile
- Colliding objects: **Highly porous dust aggregates**
 - (**Porosity** measured in: **volume of voids** / **total volume** or in **filling factor**: **volume of matter** / **total volume**)





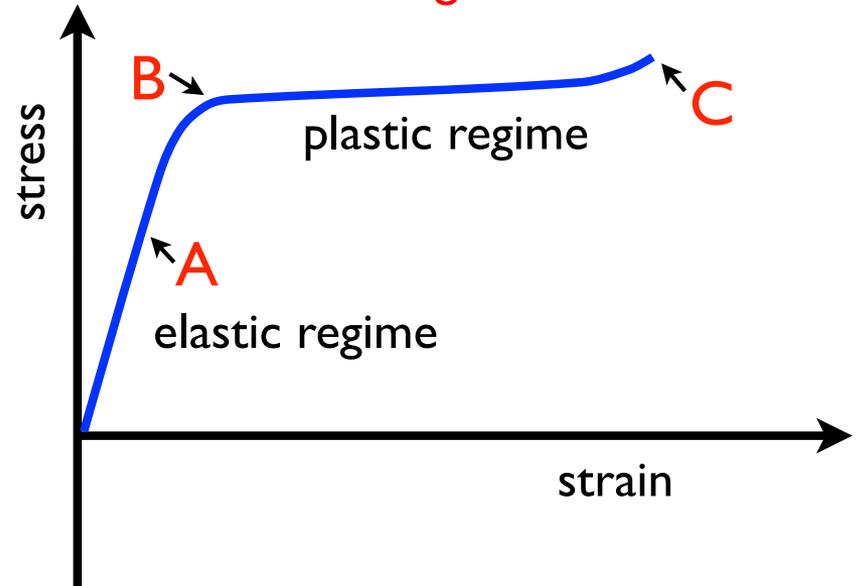
Numerical Method: Smooth Particle Hydrodynamics (SPH)

- Special version that has been extended for **solid-body mechanics** to include **elasto-plasto dynamics** with **material strength**:

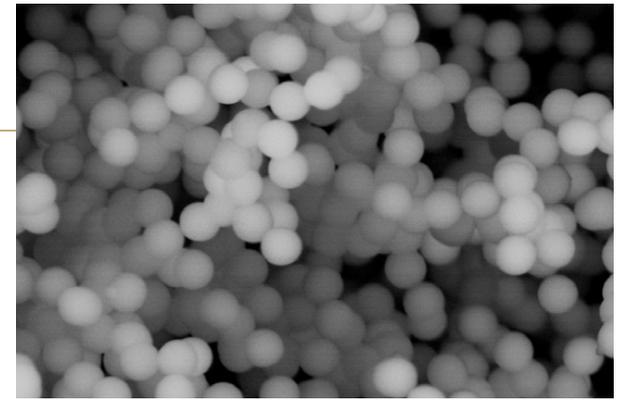
- A. **Deviatoric stress** rate proportional to strain rate (Hooke's law)
- B. **Plasticity** by modifying stresses beyond the elastic limit (Yielding relations)

- C. **Damage model** and brittle failure for **tensile** stresses

- Suitable **equation of state** for **complex materials**

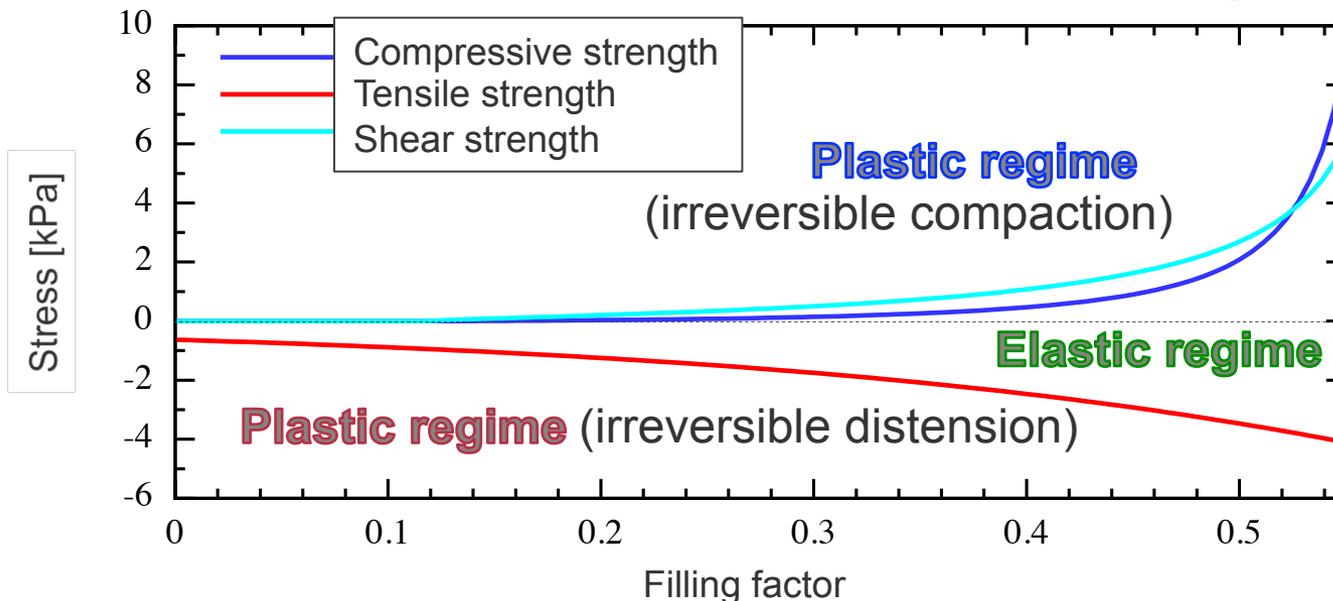


- Due to (**mesh-free**) **particle nature** of SPH: Natural **reference frame** for representing **deformations** and **fragmentation**.



Code Calibration and Modelling Porosity

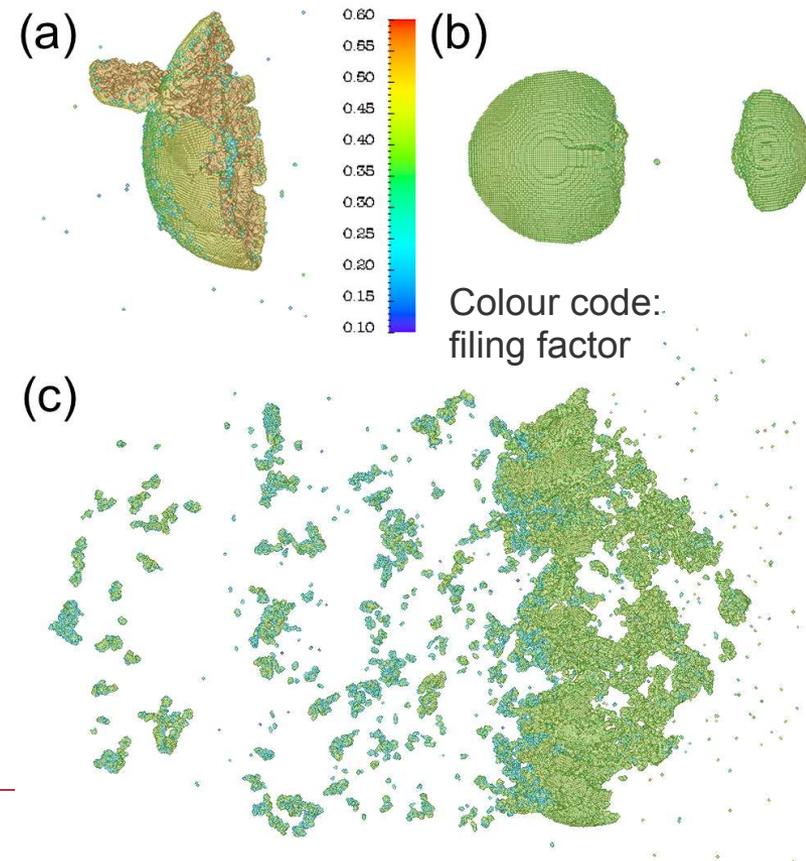
- The SPH code is **calibrated** for **agglomerates** built of **mono-disperse micron-sized spherical SiO₂ dust** (By means of lab experiments in Braunschweig; Güttler et al. 2009, Geretshauer et al. 2010)
- **Porous effects** are described by a simple **continuum model**:
 - **Elastic** and **plastic properties** depend on the **filling factor**





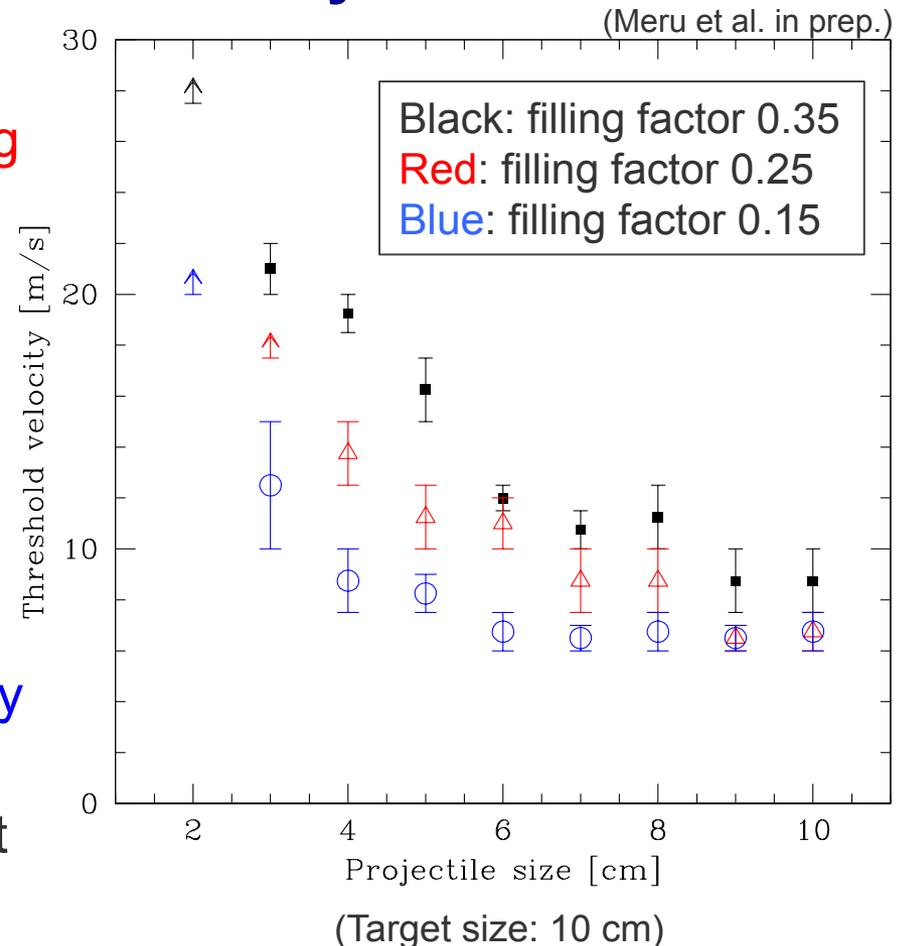
Parameter Study: Collision Velocity Threshold for Fragmentation

- Aim: Find **collision velocity** above which the **impact** results in **destruction** (fragments are **smaller** than **initial target**)
- Parameters for target and projectile:
 - Homogeneous dust spheres
 - Identical filling factors
(from 0.15 to 0.55)
 - Head-on impact
 - Different size ratios between
projectile and target (from 1:5 to 1:1)
- Examples of collisional outcome:
 - (a) **Sticking**
 - (b) **Bouncing** (with mass transfer)
 - (c) **Fragmentation**



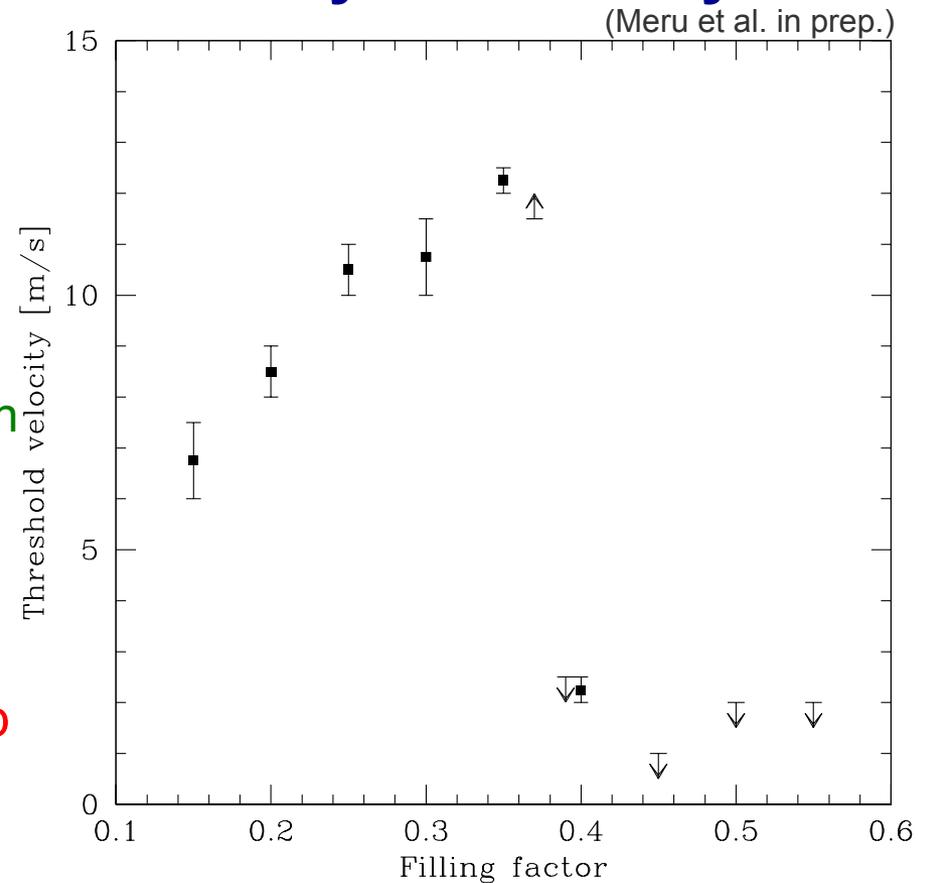
Results 1: Dependence of Fragmentation Velocity on Size Ratio

- The fragmentation threshold velocity decreases with increasing projectile size (fixed target size)
- Reason:
 - Impact energy decreases with decreasing projectile size
 - The target can absorb small projectiles as a whole
- For high and intermediate porosity (small and medium filling factors) the curves have similar shape but differ in value



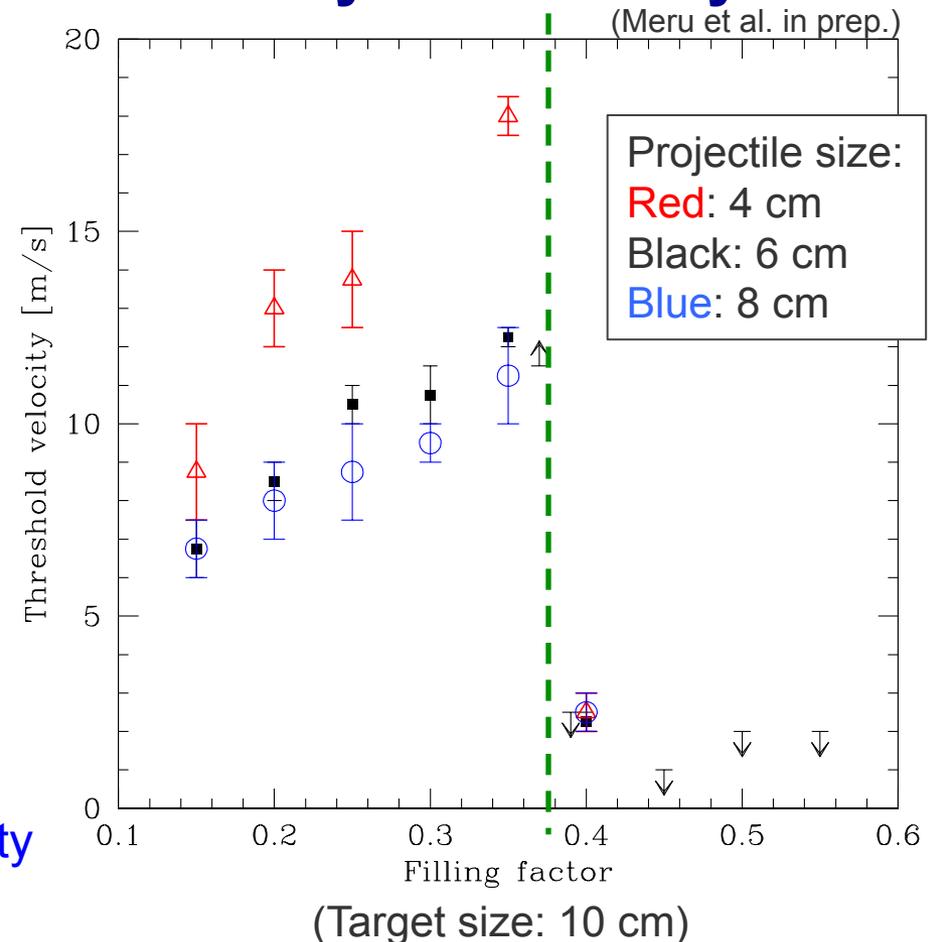
Results 2: Dependence of Fragmentation Velocity on Porosity

- At **high porosity**, the **fragmentation threshold velocity increases** with **filling factor**
 - The **compressive strength** is **low**, therefore **impact energy** can easily be **dissipated** by **plastic deformation**
 - **Tensile** and **shear strength** **increase**, therefore the **stability** of the objects **increases**
- At **filling factor** ~ 0.37 , a **sharp drop** occurs, and for **low porosity** the **threshold** is **low** ($\leq \sim 1$ m/s)



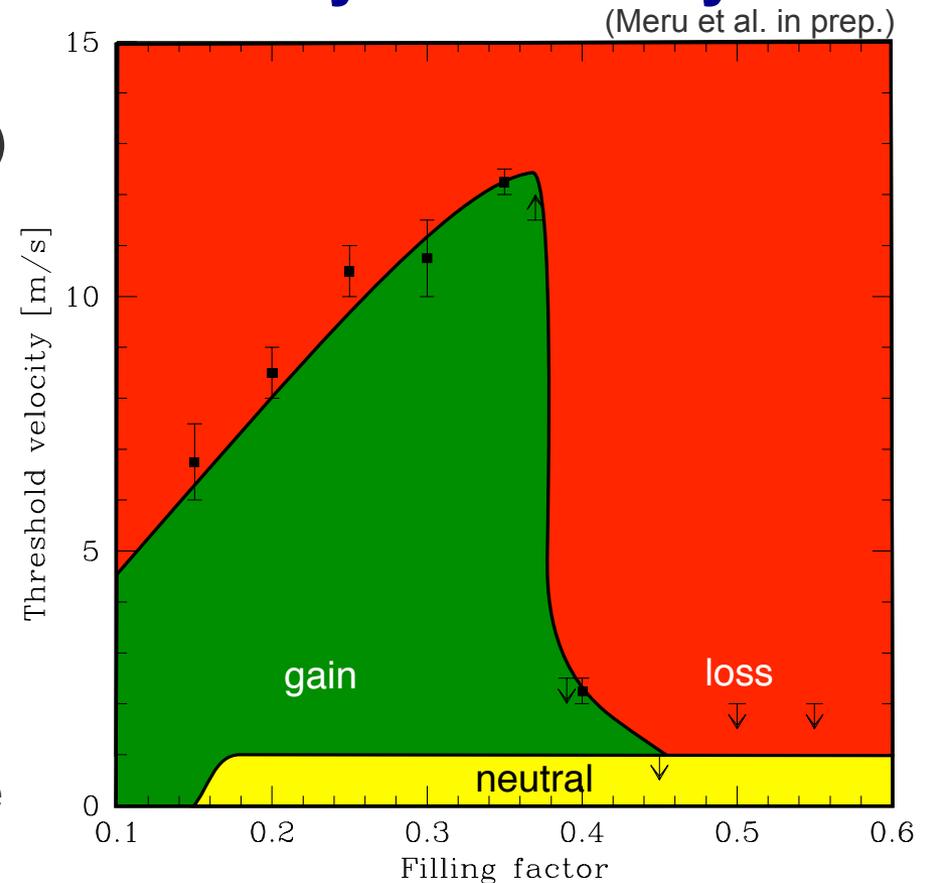
Results 2: Dependence of Fragmentation Velocity on Porosity

- The **drop** in **threshold velocity** is **independent** of **size ratio** between **projectile** and **target**
- **Complex interplay** between **elastic** and **plastic effects**:
 - With **increasing compressive strength**, **less impact energy** is **dissipated** and **more** is stored in **elastic loading**
 - With **increasing bulk modulus**, the **aggregates** become **stiffer**
 - **High strengths** lead to **larger density waves** (and **local variations**)



Results 2: Dependence of Fragmentation Velocity on Porosity

- Regimes of collisional outcome:
 - Gain: Growth (sticking, transfer)
 - Loss: Fragmentation
 - Neutral: Bouncing (partly with mass transfer)
- Higher elastic loading and stiffer aggregates increase the probability of bouncing
- Less dissipated impact energy decreases the probability of sticking
- Larger local variations in strengths due to large waves increase the probability of fragmentation

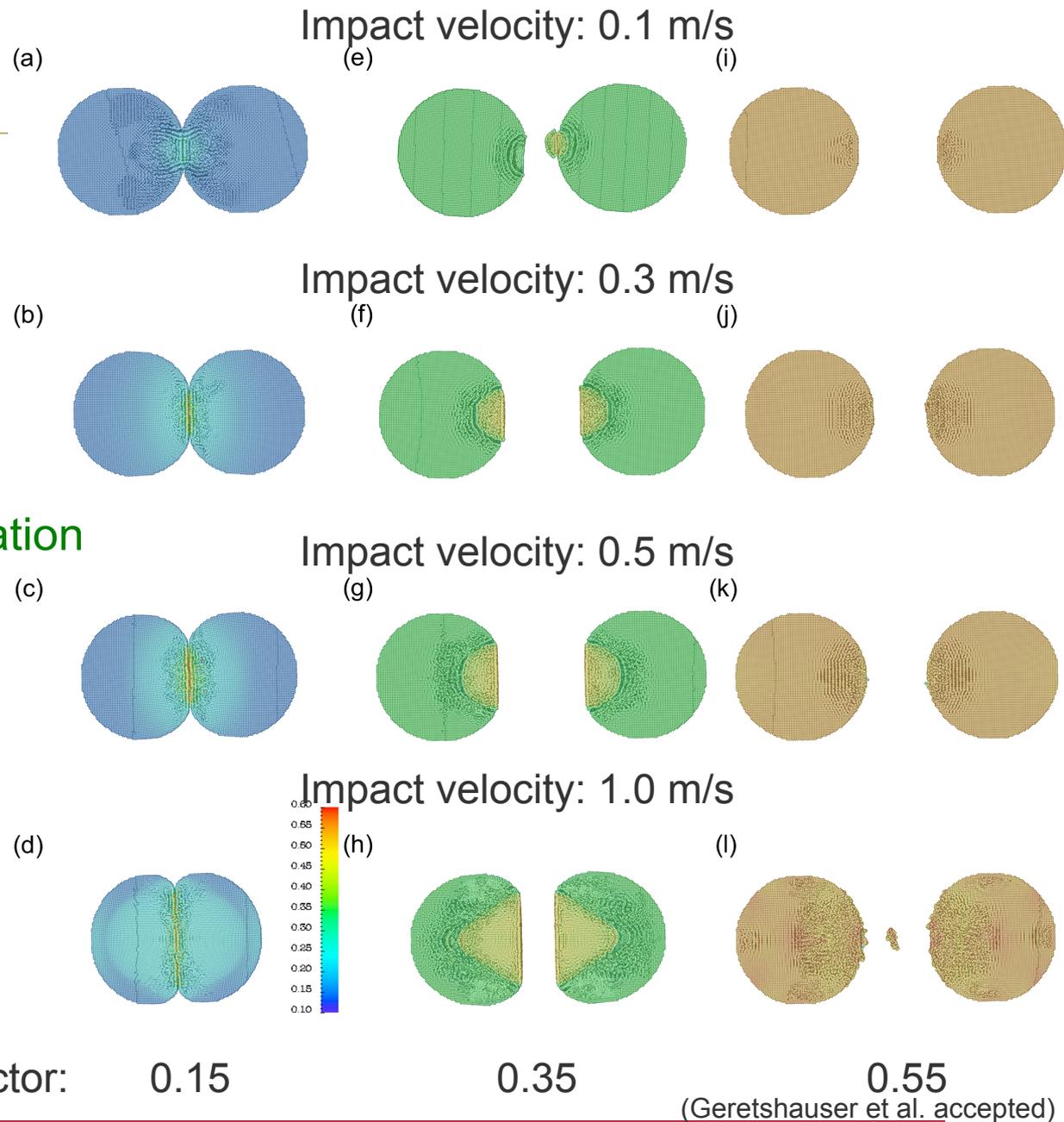


(Target size: 10 cm, projectile size: 6 cm)



Bouncing and Sticking

- **Homogeneous objects** with **low impact velocity**:
 - **High porosity**: Always **sticking** due to **dissipation** and **deformation**
 - **Medium porosity**: **Bouncing** with **plastic deformation**
 - **Low porosity**: Always **elastic bouncing** (with **small mass transfer**)

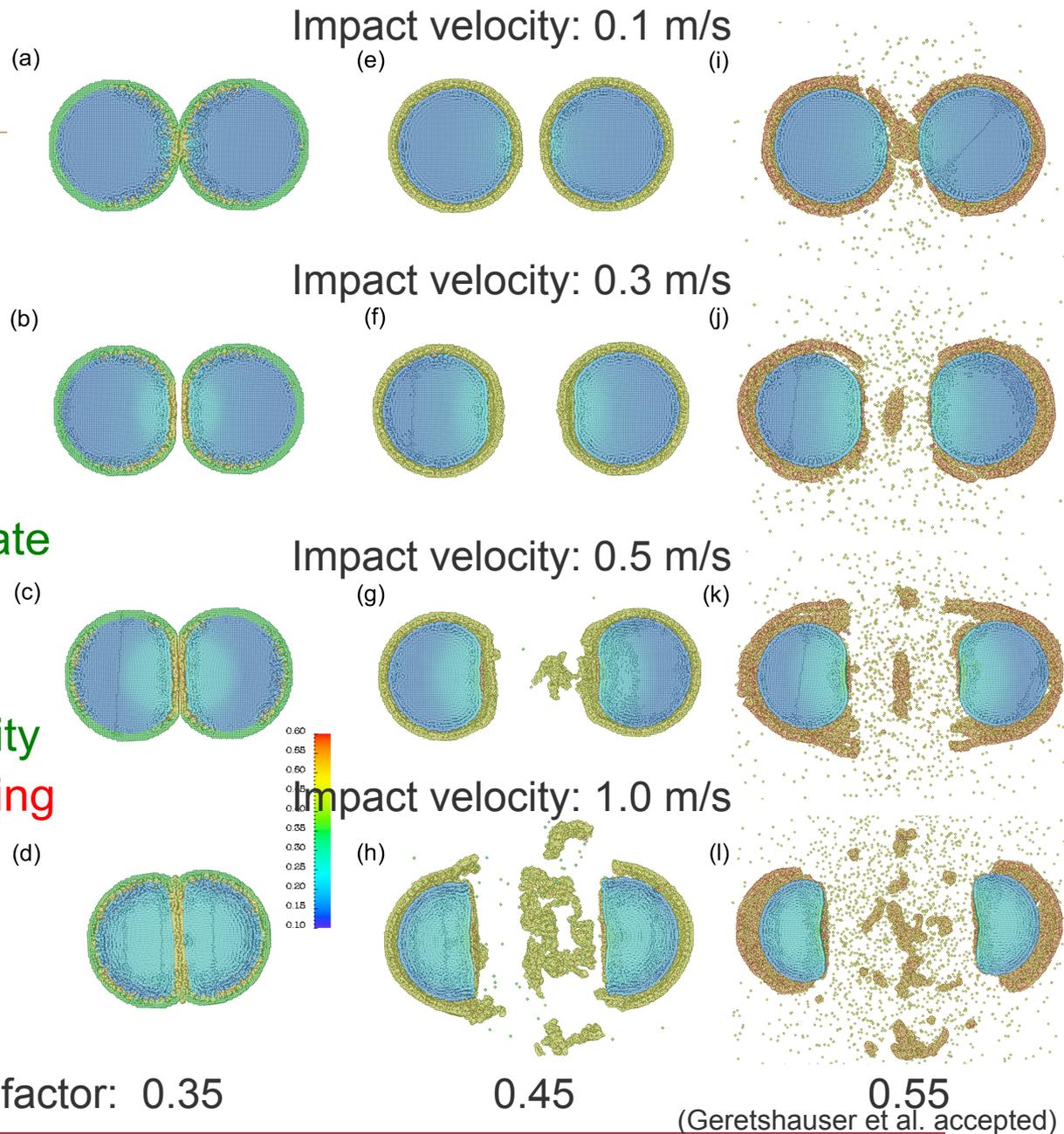




Bouncing with Hard Shells

- **Highly porous objects** (filling factor 0.15) with a **compacted shell**:

- **Shells** with **intermediate porosity** generally do **not** prevent **sticking**
- **Shells** with **low porosity** always lead to **bouncing** while the **shell** rather **breaks** than **deforms**





Summary

- For the **outcome** of **collisions** between **pre-planetesimals**, the **porosity** of the objects **is important**
- Around **intermediate porosity**, a **significant** and **sudden change in collision behaviour** is observed
- The (**quantitative**) **results** are very **sensitive to the material parameters** (\Rightarrow caution with conclusions based on special values)



Thank you.

Acknowledgements:

Support:

- DFG grant KL 650/8-2 within FOR 759

Computing time:

- bwGRiD clusters (Karlsruhe, Stuttgart, Tübingen)
- HLRS project SPH-PPC/12848